

Differentiable Cyclic Causal Discovery Under Unmeasured Confounders



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Based on work supported by

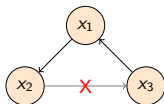


Motivation

- ▶ Causal understanding of real-world systems is crucial for prediction under unseen perturbations

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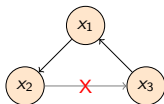
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- ▶ With a few notable exceptions, most existing work rely on the following assumptions which are often violated in practice:



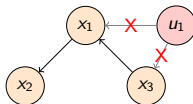
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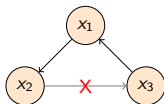
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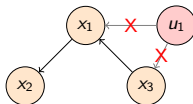
Causal sufficiency: No unmeasured confounders

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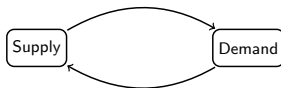


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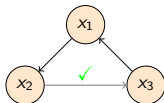
Causal sufficiency: No unmeasured confounders

- Assumptions simplify search space; Often unrealistic in practice

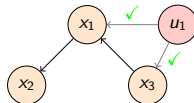


Contributions

- **DCCD-CONF**: novel differentiable causal discovery framework that handles *feedback loops*, *nonlinearity*, and *hidden confounding*



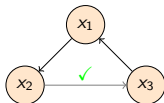
Feedback loops



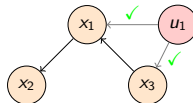
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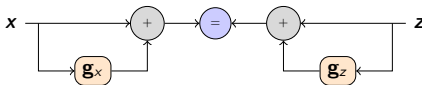


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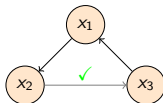
Hidden confounders

- DCCD-CONF performs maximum likelihood-based graph recovery utilizing *implicit normalizing flows*

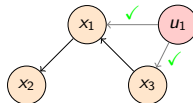


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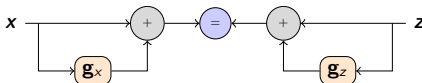


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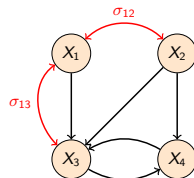
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- We show *consistency* in infinite sample regime, and showcase its practical use through synthetic and real-world experiments

Problem setup

Let $\mathcal{G} = (\mathcal{V}, \mathcal{E}, \mathcal{B})$ represent a (possibly) cyclic *Directed Mixed Graph* (DMG)



(a) Causal Graph $\mathcal{G}$

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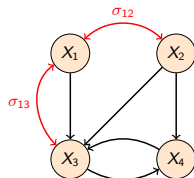
Structural Equations Model

Let Z_i 's denote the exogenous variables. Then,

$$X_i = F_i(\mathbf{X}_{\text{pa}_{\mathcal{G}}(i)}, Z_i), \quad i = 1, \dots, d.$$

$$\mathbf{Z} = (Z_1, \dots, Z_d) \sim \mathcal{N}(\mathbf{0}, \Sigma_Z), \quad (\Sigma_Z)_{ij} \neq 0 \Rightarrow i \leftrightarrow j.$$

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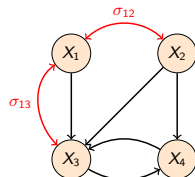
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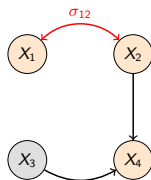
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Interventions

Hard interventions. All incoming edges to intervened nodes are removed. $\mathbf{U} \in \mathbb{R}^{d \times d}$ interventional mask matrix, then: $\mathbf{X} = \mathbf{U}\mathbf{F}(\mathbf{X}, \mathbf{Z}) + \mathbf{C}$



(a) Causal Graph $\mathcal{G}$



(b) Intervention on X_3

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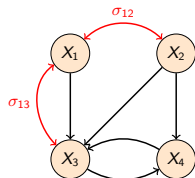
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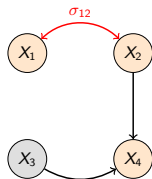
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Let $\mathbf{f}_x^{(I)} : \mathbf{X} \mapsto \mathbf{Z}$ be *forward map* under intervention, $\mathcal{U} = \mathcal{V} \setminus I$. The data likelihood is given by

$$p_{\text{do}(I)(\mathcal{G})}(\mathbf{X}) = p_I(\mathbf{C}) p_Z \left([\mathbf{f}_x^{(I)}(\mathbf{X})]_{\mathcal{U}} \right) \left| \det(\mathbf{J}_{\mathbf{f}_x^{(I)}}(\mathbf{X})) \right|,$$



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DCCD-CONF: Diff. Cyclic Causal Discovery Under Confounders

Objective Function

Given interventions $\mathcal{I} = \{I_k\}_{k \in [K]}$, we would like to learn the SEM by maximizing regularized log-data likelihood:

$$\mathcal{S}_{\mathcal{I}}(\mathcal{G}) := \sup_{\boldsymbol{\theta}, \Sigma_Z} \sum_{k=1}^K \mathbb{E}_{\mathbf{X} \sim p^{(k)}} \log p_{\text{do}(I_k)(\mathcal{G})}(\mathbf{X}) - \lambda \|\mathcal{G}\|_1.$$

Three main challenges:

1. Modeling the causal mechanism
2. Computing Log-determinant of the Jacobian
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Modeling Causal Mechanism

Causal Mechanism: $\mathbf{F}(\mathbf{x}, \mathbf{z}) = -\mathbf{g}_x(\mathbf{x}) + \mathbf{g}_z(\mathbf{z}) + \mathbf{z}$

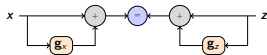


Dependency mask for graph adjacency



$\mathbf{g}_x, \mathbf{g}_z$ are modeled using *contractive NN*

The SEM forms an *implicit layer*



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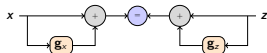


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Computing Log-det-Jacobian

Computing Log-det-Jacobian naively - $O(d^3)$

Power series expansion of $\log |\det(\mathbf{J}_{\mathbf{f}_x^{(I_k)}}(\mathbf{X}))|$ utilizing $\text{Tr}(\mathbf{J}_{\mathbf{f}_x^{(I_k)}}^m(\mathbf{X})) - O(d^2)$

Hutchinson Trace Estimator (even more reduction)

$$\text{Tr}\{\mathbf{A}\} = \mathbb{E}_{\mathbf{W}}[\mathbf{W}^\top \mathbf{A} \mathbf{W}],$$

where $\mathbb{E} \mathbf{W} = 0$, and $\mathbb{E} \mathbf{W}^2 = \mathbf{I}$.

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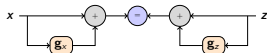


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Parameter Update

NN and graph parameters: Using *implicit function theorem*, gradients can be efficiently backpropagated

Exogenous noise covariance: Let $\mathbf{z}^{(i)} = \mathbf{f}_x(\mathbf{x}^{(i)})$, and $\mathbf{S}$ be the sample covariance of $\mathbf{Z}$. Σ_Z is obtained by solving the following convex problem:

$$\tilde{\mathcal{L}}(I_k) = \sup_{\Sigma_Z} -\text{Tr}(\mathbf{S} \Sigma_Z^{-1}) - \log |\Sigma_Z|,$$

which can be solved one column at a time as a series of LASSO regressions.

Results

Theorem. Let $\mathcal{I} = \{I_k\}_{k=1}^K$ be a family of interventional targets, let $\mathcal{G}^*$ denote the ground truth directed mixed graph, let $p^{(k)}$ denote the data generating distribution for I_k , and $\hat{\mathcal{G}} := \arg \max_{\mathcal{G}} \mathcal{S}(\mathcal{G})$. Then, under suitable assumptions and a suitably chosen $\lambda > 0$, we have that $\hat{\mathcal{G}}$ is $\mathcal{I}$ -Markov equivalent to $\mathcal{G}^*$.

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Gene regulatory network: Data was taken from Frangieh et al (2021)¹. Contains gene expressions taken from 218,331. Choose 61 genes from around 20,000.

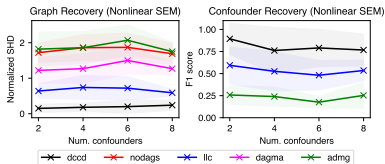
Table: Performance comparison with respect to I-NLL

Method	Control	Co-Culture	IFN- γ
DCCD-CONF	1.375 (0.103)	1.245 (0.039)	1.235 (0.338)
NODAGS	1.465 (0.015)	1.406 (0.012)	1.504 (0.009)
LLC	1.385 (0.039)	1.325 (0.029)	1.430 (0.048)
DCDI	1.523 (0.036)	1.367 (0.018)	1.517 (0.041)

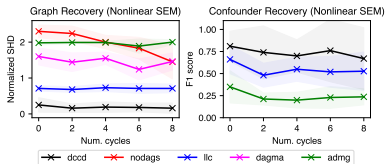
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Results - Ablation Study

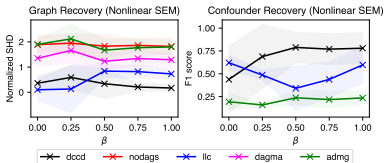
Synthetic Experiments: All experiments were performed on $d = 10$ node graphs. DCCD-CONF was compared with NODAGS-Flow, LLC, DAGMA, DCD



(a) Ablation - Confounders



(b) Ablation - Cycles



(c) Ablation - Nonlinearity